

# Introduction to Personalized Medicine and Dynamic Treatment Regimes

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# What is personalized medicine?



# What is personalized medicine?



## *Personalized Medicine*

Source of graphic: <http://www.personalizedmedicine.com/>

## One size does not fit all:

- Multiple *treatment options*
- Patient *heterogeneity*

**Basic premise:** A *patient's characteristics* are implicated in which *treatment option* s/he should receive

- Genetic/genomic, other omic, . . .
- Demographic, physiologic/clinical measures, medical history, . . .

## Subgroup identification/targeted treatment:

- Are there subgroups of patients who are *more likely* to do better on one treatment than on another?
- Can *biomarkers* be developed to identify such patients?
- Can a treatment be developed that *targets* a subgroup that is very likely to benefit from that treatment?

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**Focus:** Targeting treatment to *subgroups* of the population

- “*Right patient for the treatment*”

# Another perspective on personalized medicine

**Clinical practice:** Clinicians make (a series of) *treatment decision(s)* over the course of a patient's disease or disorder

- Key *decision points* in the disease process
- *Fixed schedule*, *milestone* in the disease process, *event* necessitating a decision
- Multiple *treatment options* at each
- *Accrued information* on the patient

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**Focus:** *Given information on patient's characteristics*, can we determine the treatment(s) from among the available options most likely to benefit him/her?

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**This is the perspective we will take**

## How are these decisions made?

- *Clinical judgment*
- *Practice guidelines* based on combining *study results* and *expert opinion*
- Synthesize all *information* on a patient up to the point of the decision to determine the *next treatment action*

## How can statistics and statistical thinking be used to formalize clinical decision-making?

# Dynamic treatment regime

**Formalizing personalized medicine:** At any *decision*

- Need a *rule* that takes as *input* the *accrued information* on the patient to that point and *outputs* the next treatment from among the *possible options*

**Dynamic treatment regime:** A set of formal such *rules*, each corresponding to a *decision point*

- *Dynamic* because the treatment action *varies* depending on the *accrued information*

# Single decision

**Simple example:** Which treatment to give to patients who present with primary operable *breast cancer*?

- *Treatment options*: L-phenylalanine mustard and 5-fluorouracil ( $c_1$ ) or  $c_1$  + tamoxifen ( $c_2$ )
- *Information*: age, progesterone receptor level (PR)

**Example rule:** “If age < 50 years and PR < 10 fmol, give  $c_1$  (coded as 1); otherwise, give  $c_2$  (coded as 0)”

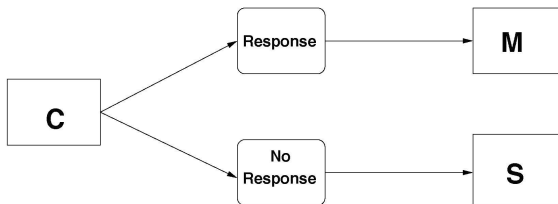
- *Mathematically*, the rule  $d$  is (*rectangular region*)

$$d(\text{age}, \text{PR}) = I(\text{age} < 50 \text{ and } \text{PR} < 10)$$

- *Alternatively*: Rules of form (*hyperplane*)

$$d(\text{age}, \text{PR}) = I\{\text{age} + 8.7 \log(\text{PR}) - 60 > 0\}$$

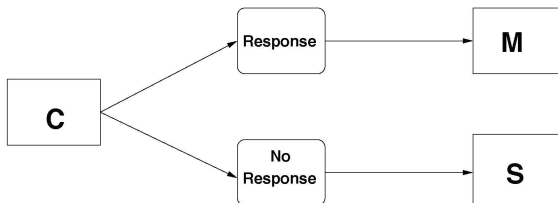
# Multiple decision points



## Two decision points:

- *Decision 1*: Induction chemotherapy (options  $c_1, c_2$ )
- *Decision 2*:
  - ▶ Maintenance treatment for patients who *respond* (options  $m_1, m_2$ )
  - ▶ Salvage chemotherapy for those who *don't* (options  $s_1, s_2$ )

# Multiple decision points



- *At baseline*: Information  $x_1$  (*accrued information*  $h_1 = x_1$ )
- *Decision 1*: Two *options*  $\{c_1, c_2\}$ ; *rule 1*:  $d_1(x_1) \Rightarrow x_1 \rightarrow \{c_1, c_2\}$
- *Between decisions 1 and 2*: Collect *additional information*  $x_2$ , including *responder status*
- *Accrued information*  $h_2 = \{x_1, \text{chemotherapy at decision 1}, x_2\}$
- *Decision 2*: Four *options*  $\{m_1, m_2, s_1, s_2\}$ ; *rule 2*:  $d_2(h_2) \Rightarrow h_2 \rightarrow \{m_1, m_2\}$  (responder),  $h_2 \rightarrow \{s_1, s_2\}$  (nonresponder)
- *Regime*:  $d = (d_1, d_2)$

# Summary

## Single decision: 1 decision point

- *Baseline information*  $x \in \mathcal{X}$
- Set of *treatment options*  $a \in \mathcal{A}$
- *Decision rule*  $d(x)$ ,  $d : \mathcal{X} \rightarrow \mathcal{A}$
- *Treatment regime*:  $d$

## Multiple decisions: $K$ decision points

- *Baseline information*  $x_1$ , *intermediate information*  $x_k$  between decisions  $k - 1$  and  $k$ ,  $k = 2, \dots, K$
- Set of *treatment options* at each decision  $k$ :  $a_k \in \mathcal{A}_k$
- *Accrued information*  $h_1 = x_1 \in \mathcal{H}_1$ ,

$$h_k = \{x_1, a_1, x_2, a_2, \dots, x_{k-1}, a_{k-1}, x_k\} \in \mathcal{H}_k, \quad k = 2, \dots, K$$

- *Decision rules*  $d_1(h_1), d_2(h_2), \dots, d_K(h_K)$ ,  $d_k : \mathcal{H}_k \rightarrow \mathcal{A}_k$
- *Treatment regime*  $d = (d_1, d_2, \dots, d_K)$

# “Best” treatment regime?

**Obviously:** There is an *infinitude* of possible regimes  $d$

- $\mathcal{D}$  = class of *all possible* dynamic treatment regimes
- Can we find the “*best*” set of rules; i.e., the “*best*” dynamic treatment regime in  $\mathcal{D}$ ?
- How to define “*best?*”

**Approach:** Formalize *best* using ideas from *causal inference*



**Outcome:** There is a *clinical outcome* by which treatment *benefit* can be assessed

- Survival time, CD4 count, indicator of no myocardial infarction within 30 days, . . .
- *Larger outcomes* are *better*

# Defining “best”

**An optimal regime  $d^{opt}$ :** Should satisfy

- If *all patients* in the *population* were to receive treatment according to  $d^{opt}$ , the *expected outcome* for the population would be *as large as possible*
- If an individual patient *were to receive treatment* according to  $d^{opt}$ , his/her *expected outcome* would be *as large as possible given the information available on him/her*

**Formalize this...**

# Optimal regime for single decision

**For simplicity:** Consider regimes involving a *single decision* with *two* treatment options (coded as 0 and 1)

- $\mathcal{A} = \{0, 1\}$
- *Baseline information*  $x \in \mathcal{X}$

**Treatment regime:** A single *rule*  $d(x)$

- $d : \mathcal{X} \rightarrow \{0, 1\}$
- $d \in \mathcal{D}$ , the class of *all* regimes

# Potential outcomes

**Treatments 0 and 1:** We can hypothesize *potential outcomes*

- $Y^*(1)$  = outcome that *would be achieved* if a patient *were to receive* treatment 1
- $Y^*(0)$  similarly
- $E\{Y^*(1)\}$  is the *expected outcome* if *all patients* in the population were to receive 1;  $E\{Y^*(0)\}$  similarly

**In fact:** In a *randomized trial* comparing 0 and 1, the *question of interest* can be stated as

“Is the *expected outcome* if *all patients in the population* were to receive 0 *different from* that if they all were to receive 1 instead?”

- *Comparison* of  $E\{Y^*(1)\}$  and  $E\{Y^*(0)\}$

# Potential outcome for a regime

**Potential outcome for a regime:** For any  $d \in \mathcal{D}$ , define  $Y^*(d)$  to be the *potential outcome* for a patient with *baseline information*  $X$  if s/he were to receive treatment *in accordance with regime*  $d$

$$Y^*(d) = Y^*(1)d(X) + Y^*(0)\{1 - d(X)\}$$

- *Recall:*  $d: \mathcal{X} \rightarrow \{0, 1\}$
- *Potential outcome for regime*  $d$  for a patient with information  $X$  is the potential outcome for the treatment option *dictated by*  $d$

# Potential outcome for a regime

**In general:** For a *single decision* with set of treatment options  $\mathcal{A}$  with elements  $a$

- *Potential outcomes*  $Y^*(a)$ ,  $a \in \mathcal{A}$
- *Potential outcome* for regime  $d \in \mathcal{D}$

$$Y^*(d) = \sum_{a \in \mathcal{A}} Y^*(a) I\{d(X) = a\}$$

# Optimal dynamic treatment regime

## Thus:

- $E\{Y^*(d)|X = x\}$  is the *expected outcome* for a patient with *information*  $x$  if s/he were to receive treatment according to regime  $d \in \mathcal{D}$
- $E\{Y^*(d)\} = E[E\{Y^*(d)|X\}]$  is the expected (average) outcome for the *population* if *all patients* were to receive treatment according to regime  $d \in \mathcal{D}$

**Optimal regime:**  $d^{opt}$  is a regime in  $\mathcal{D}$  such that

- $E\{Y^*(d)\} \leq E\{Y^*(d^{opt})\}$  for all  $d \in \mathcal{D}$
- $E\{Y^*(d)|X = x\} \leq E\{Y^*(d^{opt})|X = x\}$  for all  $d \in \mathcal{D}$  and all  $x \in \mathcal{X}$

# Optimal dynamic treatment regime

**Simplest case:**  $\mathcal{A} = \{0, 1\}$

$$Y^*(d) = Y^*(1)d(X) + Y^*(0)\{1 - d(X)\}$$

- *Thus*

$$\begin{aligned} E\{Y^*(d)\} &= E\left[E\{Y^*(d)|X\}\right] \\ &= E\left[E\{Y^*(1)|X\}d(X) + E\{Y^*(0)|X\}\{1 - d(X)\}\right] \end{aligned}$$

- It *follows* that

$$d^{opt}(x) = I\left[E\{Y^*(1)|X = x\} > E\{Y^*(0)|X = x\}\right]$$



# Important philosophical point

## Distinguish between:

- The “*best*” treatment for a patient
- The “*best*” treatment *decision* for a patient *given the information available on the patient*

**Best treatment for a patient:** Option  $a^{best} \in \mathcal{A}$  corresponding to the *largest*  $Y^*(a)$  for the patient

## Best treatment given the information available:

- We *cannot* hope to determine  $a^{best}$  because we can never see *all* potential outcomes on a given patient
- We *can* hope to make the *optimal decision* given the *information available*, i.e., find  $d^{opt}$  that makes  $E\{Y^*(d)\}$  and  $E\{Y^*(d)|X = x\}$  *as large as possible*

# Statistical problem

**Goal:** Given *data* from a clinical trial or observational study, *estimate* an *optimal regime*  $d^{opt}$  satisfying this definition

**Observed data:** Single decision,  $K = 1$ ,  $\mathcal{A} = \{0, 1\}$ .

$$(X_i, A_i, Y_i), \quad i = 1, \dots, n \quad \text{iid}$$

- $X$  = *baseline* information
- $A$  = treatment *actually received*
- $Y$  = *observed* outcome

**Required:**

- *Optimal regime* is defined in terms of *potential outcomes*
- Must *express equivalently* in terms of *observed data*

# Statistical problem

## Consistency assumption:

$$Y = Y^*(1)A + Y^*(0)(1 - A)$$

## No unmeasured confounders assumption:

$$Y^*(0), Y^*(1) \perp\!\!\!\perp A_1 \mid X_1$$

- Automatically satisfied in a *clinical trial*
- *Unverifiable* but necessary in an *observational study*

# Statistical problem

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- Automatically satisfied in a *clinical trial*
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## Under these assumptions:

$$E\{Y^*(d)\} = E\left[ E(Y|X_1, A = 1)d(X_1) + E(Y|X_1, A = 0)\{1 - d(X_1)\} \right]$$

- *Butch* will show how this leads to an estimator for  $d^{opt}$

# Multiple decision points

**Potential outcomes:** Same ideas, only more *complicated*

- *Baseline information*  $X_1$
- $K$  decisions, set of *treatment options*  $\mathcal{A}_k$ ,  $k = 1, \dots, K$
- $\bar{a}_k = (a_1, \dots, a_k) =$  possible *treatment history* through decision  $k$ , taking values in  $\bar{\mathcal{A}}_k = \mathcal{A}_1 \times \dots \times \mathcal{A}_k$
- $X_k^*(\bar{a}_{k-1}) =$  intermediate information between decisions  $k - 1$  and  $k$  that *would arise* for a patient if s/he *were to receive* treatment history  $\bar{a}_{k-1}$
- $Y^*(\bar{a}_K) =$  outcome that *would be achieved* for a patient if s/he *were to receive* treatment history  $\bar{a}_K$
- *Potential outcomes* under treatment history  $\bar{a}_K$

$$X_2^*(a_1), X_3^*(\bar{a}_2), \dots, X_K^*(\bar{a}_{K-1}), Y^*(\bar{a}_K)$$

# Multiple decision points

## Potential outcomes for regime $d = (d_1, \dots, d_K)$ :

- Write  $\bar{d}_k = (d_1, \dots, d_k) =$  *first  $k$  rules* in  $d$ ,  $\bar{d}_K = d$
- Write  $\bar{x}_k$  similarly
- $h_k = (x_1, a_1, x_2, \dots, a_{k-1}, x_k) = (\bar{x}_k, \bar{a}_{k-1})$
- With  $X_1 = x_1 = h_1$

$$d_1(h_1) = a_1, X_2^*(d_1) = X_2^*(a_1) = x_2, d_2(h_2) = a_2,$$

$$X_3^*(\bar{d}_2) = X_3^*(\bar{a}_2) = x_3, \dots, d_{K-1}(h_{K-1}) = a_{K-1},$$

$$X_K^*(\bar{d}_{K-1}) = X_K^*(\bar{a}_{K-1}) = x_K, d_K(h_K) = a_K, Y^*(d) = Y^*(\bar{a}_K) = y$$

# Multiple decision points

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$$d_1(h_1) = a_1, X_2^*(d_1) = X_2^*(a_1) = x_2, d_2(h_2) = a_2,$$

$$X_3^*(\bar{d}_2) = X_3^*(\bar{a}_2) = x_3, \dots, d_{K-1}(h_{K-1}) = a_{K-1},$$

$$X_K^*(\bar{d}_{K-1}) = X_K^*(\bar{a}_{K-1}) = x_K, d_K(h_K) = a_K, Y^*(d) = Y^*(\bar{a}_K) = y$$

- $X_k^*(\bar{d}_{k-1})$  is the information that *would arise* between decisions  $k - 1$  and  $k$  if a patient *were to receive* the treatments dictated by the first  $k - 1$  rules in  $d$
- $Y^*(d)$  is the outcome a patient *would achieve* if s/he *were to receive* the  $K$  treatments according to the  $K$  rules in  $d$

# Optimal dynamic treatment regime

**Thus:** For  $K \geq 1$  decision points

- $E\{Y^*(d)|X_1 = x_1\}$  is the *expected outcome* for a patient with *baseline information*  $x_1$  if s/he were to receive all  $K$  subsequent treatments according to regime  $d \in \mathcal{D}$
- $E\{Y^*(d)\} = E[E\{Y^*(d)|X\}]$  is the expected (average) outcome for the *population* if *all patients* were to receive all  $K$  treatments according to regime  $d \in \mathcal{D}$

**Optimal regime:**  $d^{opt}$  is a regime in  $\mathcal{D}$  such that

- $E\{Y^*(d)\} \leq E\{Y^*(d^{opt})\}$  for all  $d \in \mathcal{D}$
- $E\{Y^*(d)|X_1 = x_1\} \leq E\{Y^*(d^{opt})|X_1 = x_1\}$  for all  $d \in \mathcal{D}$  and all  $x_1 \in \mathcal{X}_1 = \mathcal{H}_1$



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**Observed data:**  $K$  decisions

$(X_{1i}, A_{1i}, X_{2i}, A_{2i}, \dots, X_{(K-1)i}, A_{(K-1)i}, X_{Ki}, A_{Ki}, Y_i), \quad i = 1, \dots, n, \quad iid$

- $Y =$  *observed* outcome
- $A_k, k = 1, \dots, K =$  treatment *received* at decision  $k$
- $X_k, k = 2, \dots, K =$  *intermediate information* observed between decisions  $k - 1$  and  $k$
- $H_k = (X_1, A_1, X_2, \dots, A_{k-1}, X_k), k = 2, \dots, K =$  *accrued information* to decision  $k$

**Consistency:**  $X_k = X_k^*(\bar{A}_{k-1}), k = 2, \dots, K; Y = Y^*(\bar{A}_K)$

## Critical assumption: *Sequential randomization*

- Generalization of *no unmeasured confounders*
- Treatment received at *each decision*  $k = 1, \dots, K$  is *statistically independent* of potential outcomes that would be achieved under all treatment options *at all decisions* given the *accrued information*  $H_k$

$$W^* = \{X_2^*(a_1), X_3^*(\bar{a}_2), \dots, X_k^*(\bar{a}_{k-1}), \dots, X_K^*(\bar{a}_{K-1}), Y^*(\bar{a}_K) \text{ for all } \bar{a}_K \in \bar{\mathcal{A}}_K\}$$

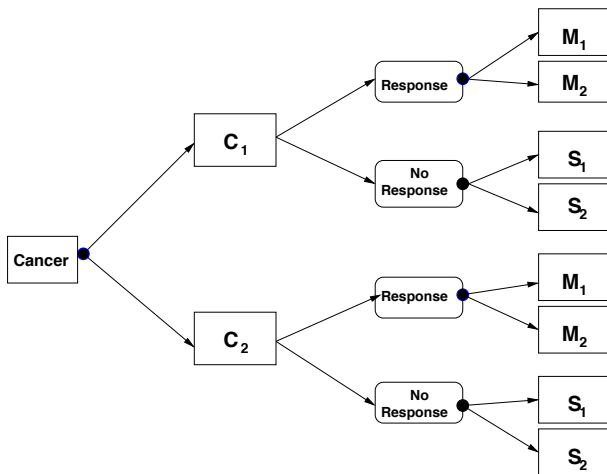
$$W^* \perp\!\!\!\perp A_k | H_k$$

- *Butch* will characterize the form of  $d^{opt}$  and show how this leads to an expression for  $d^{opt}$  in terms of *observed data* and *estimators* for  $d^{opt}$

## Studies:

- Longitudinal observational
- Sequential, Multiple Assignment, Randomized Trial

## Cancer example: Randomization at ●s



*Sequential randomization* automatically holds

# Summary

- Formalizing this problem in terms of *potential outcomes* yields *precise definition* of an optimal regime
- And *clarifies* what must be assumed about *observed data* for them to be used to *estimate* an optimal regime

Schulte, P. J., Tsiatis, A. A., Laber, E. B., and Davidian, M. (2014). Q- and A-learning methods for estimating optimal dynamic treatment regimes. *Statistical Science*, in press.