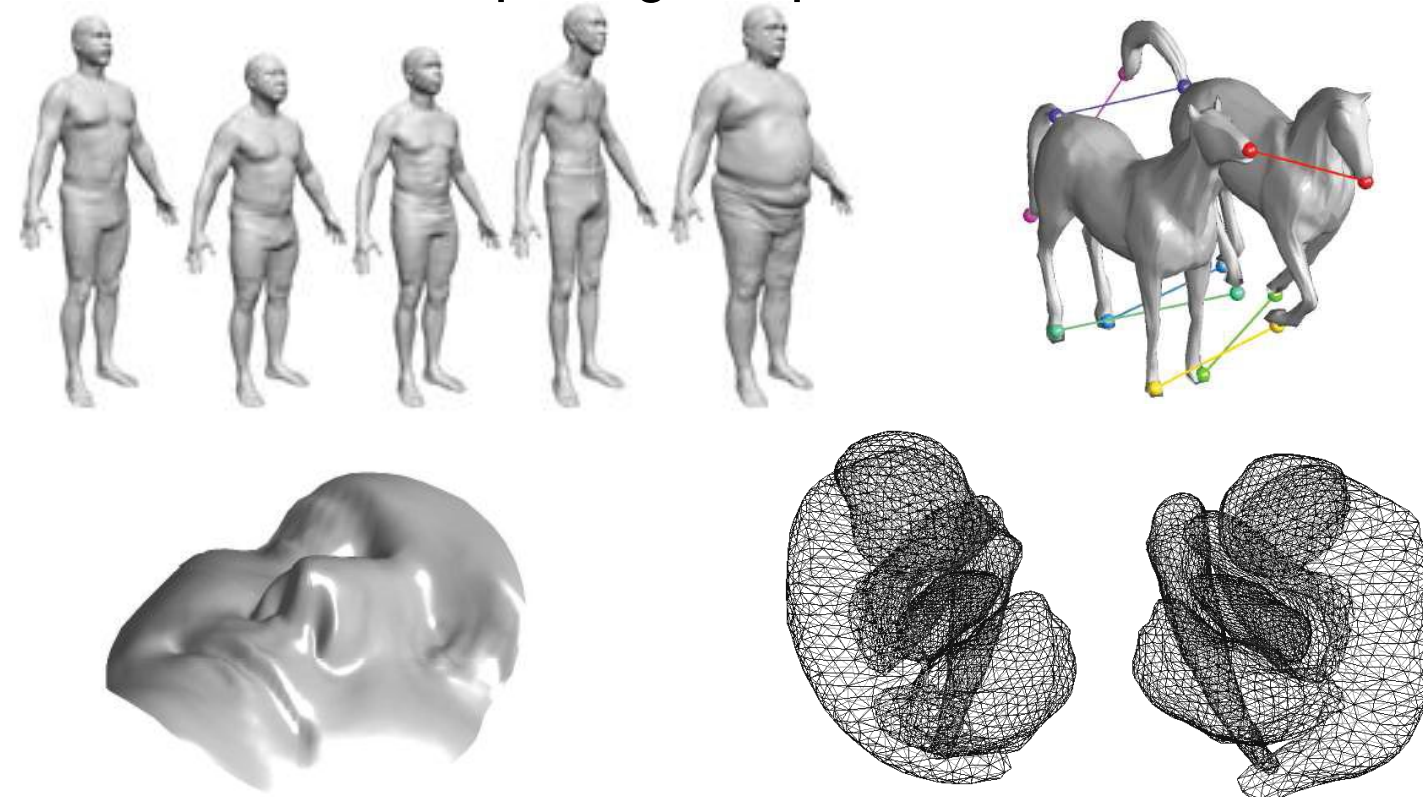


INTRODUCTION

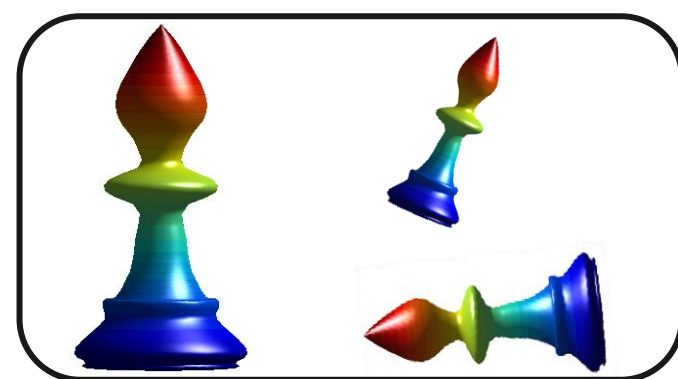
- Goal: Many applications concern with capturing variability within and across shape classes
- Main focus is on statistical shape analysis in addition to comparing shapes



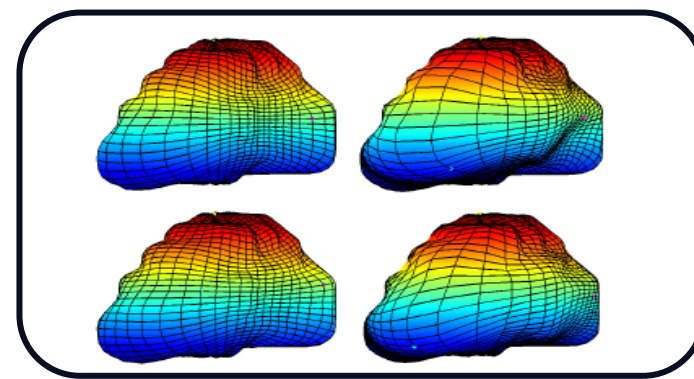
Shapes As Equivalence Classes

- **Shape:** geometrical information after modding out some desired invariances

Translation/Scale/Rotation



Re-parameterization

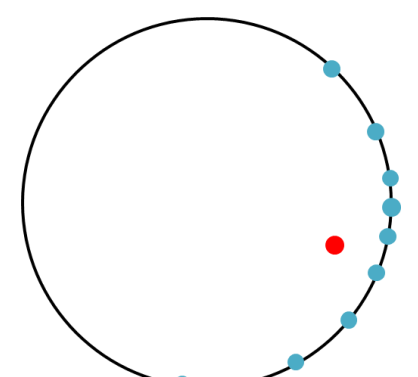


Surfaces with the same shape: $f_1 \sim f_2$

Shape Spaces Are Non-Euclidean

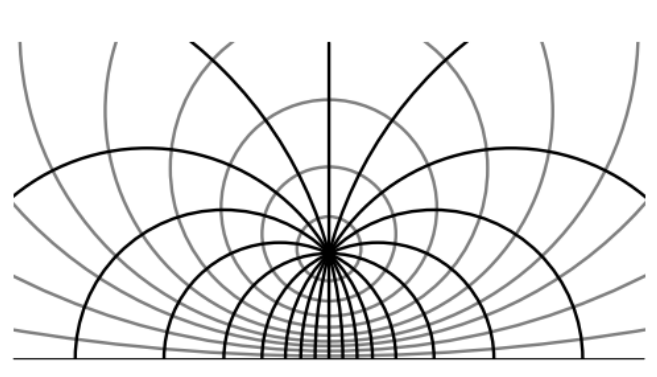
- Space of shapes, $S = \{[f] | f \in L^2\}$
- Shape spaces are non-Euclidean

1-Sphere



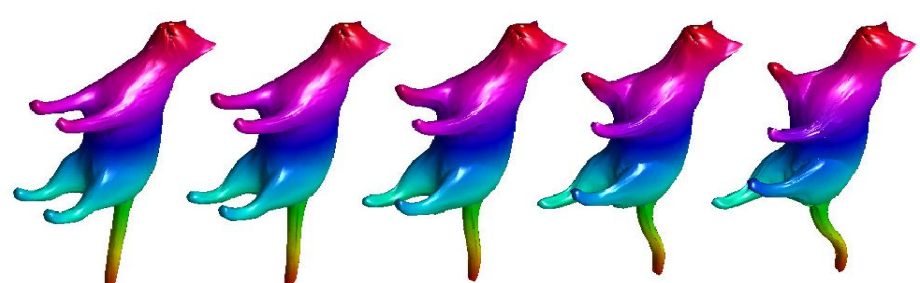
Computing mean.

Hyperbolic Plane



'Straight' lines and parallelism.

- Generally, no closed form for geodesics



A 'straight line' in the shape space.

SRNF of Surfaces

Definition. Given a spherical parameterized closed surfaces, $f: S^2 \rightarrow R^3$, its Square Root Normal Field (SRNF) is a mapping $f \mapsto Q(f)$, such that for all $s \in S^2$,

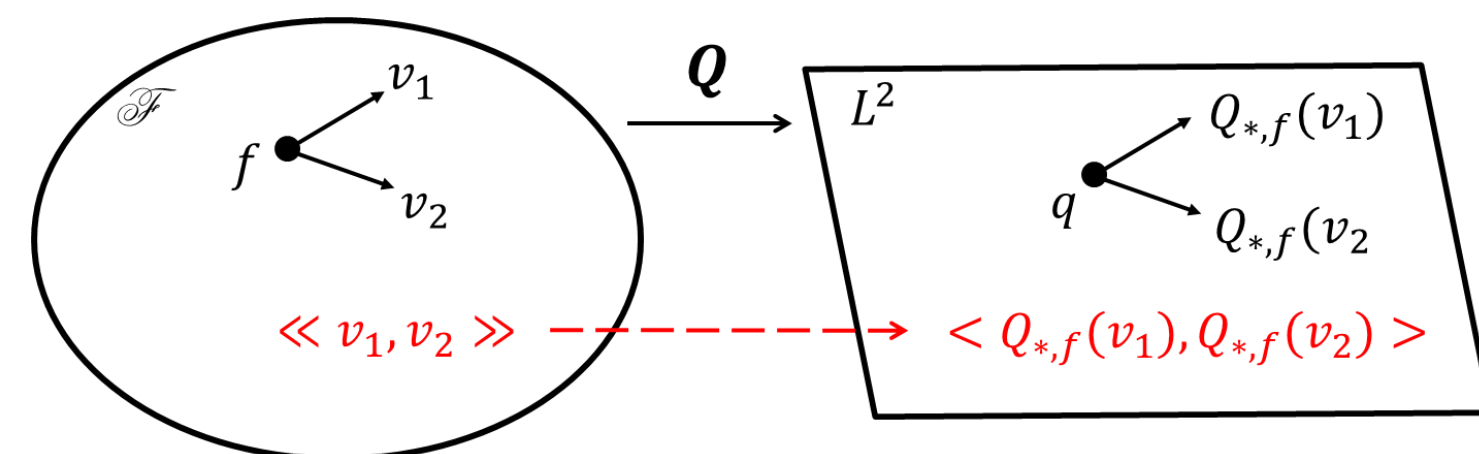
$$Q(f)(s) = \frac{n(s)}{|n(s)|^{1/2}}, \text{ where } n(s) = f_u(s) \times f_v(s).$$

Advantages of SRNF

- The L^2 metric on F does not preserve distance, $\|f_1 - f_2\| \neq \|(f_1, \gamma) - (f_2, \gamma)\|$
- The shape-invariant variables act on SRNFs by isometries,

$$\|q_1 - q_2\| = \|(q_1, \gamma) - (q_2, \gamma)\|$$

- The *elastic metric* becomes L^2 on SRNFs



- The *elastic metric* is physically interpretable

$$\frac{1}{4} \int_D \frac{\delta r_1(s) \delta r_2(s)}{r(s)} ds + \int_D \langle \delta \tilde{n}_1(s), \delta \tilde{n}_2(s) \rangle r(s) ds$$

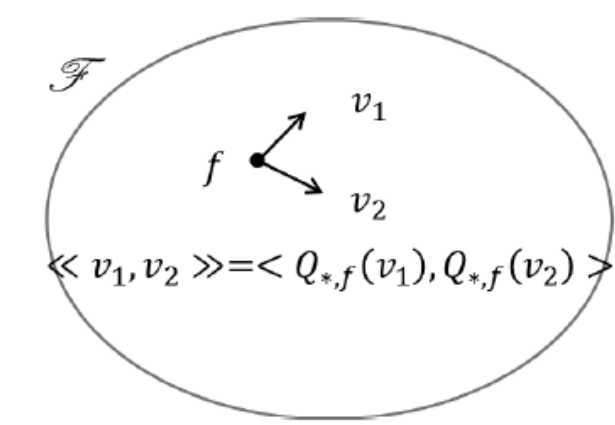
Patch area

Normal direction

Proposed Framework

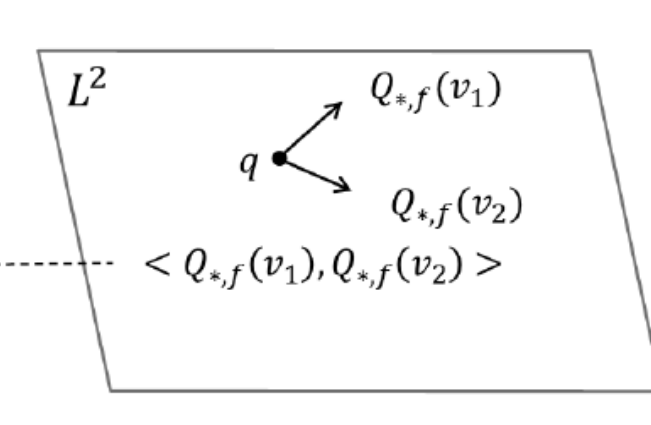
- In the absence of invertibility, some of the advantages of the SRNF are lost

Previous Calculation



Numerically Complicated

Proposed Calculation



Simplified Computation

Numerical Inversion by Optimization

- The energy function

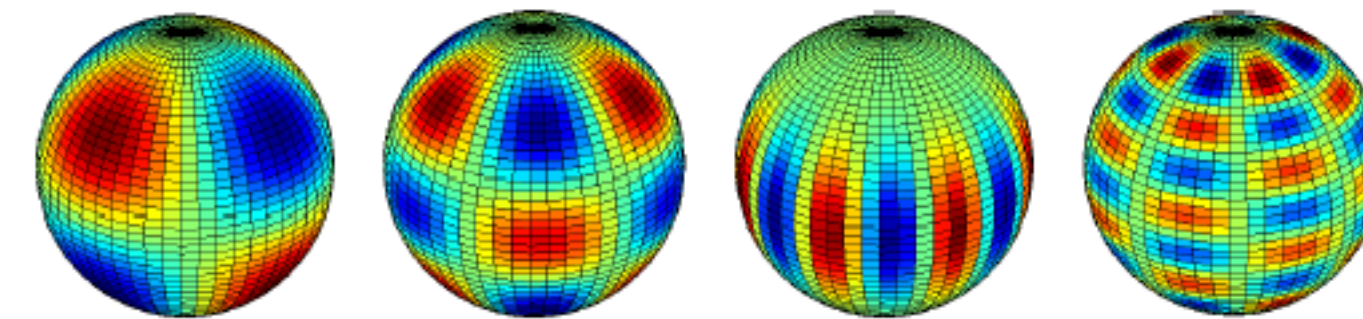
$$E(f; q) = \|Q(f) - q\|_2^2$$

- Given an SRNF, q_o , the original shape f_o s.t. $Q(f_o) = q_o$ is *estimated* as

$$f^* = \operatorname{argmin}_{f \in F} E(f; q_o)$$

- Gradient descent

$$\nabla E(f; q) = \sum_{b \in B} \nabla_b E(f; q_o) \cdot b$$



Examples of Spherical Harmonic Basis

Simplified Calculation

- Simplified analysis
 - Geodesic computation (deformation)
 - Mean, PCA
 - Random sampling

Computing Mean

Previous

Algorithm 1 Let μ_f^0 be an initial estimate. Set $j = 0$.

1. Register f_1, \dots, f_n to μ_f^j .
2. For each $i = 1, \dots, n$, construct a geodesic to connect f_i to μ_f^j and evaluate $v_i = \exp_{\mu_f^j}^{-1}(q_i)$.
3. Compute the average direction $\bar{v} = \frac{1}{n} \sum_{i=1}^n v_i$.
4. If $\|\bar{v}\|$ is small, stop. Else, update $\mu_f^{j+1} = \exp_{\mu_f^j}(\bar{v})$ by shooting a geodesic, $\epsilon \ll 0$, small.
5. Set $j = j + 1$ and return to Step 1.

n geodesics per iteration

Proposed

Algorithm 2 Let $\bar{q} = Q(\mu_f^0)$ with μ_f^0 as an initial estimate. Set $j = 0$.

1. Register $Q(f_1), \dots, Q(f_n)$ to \bar{q} .
2. Update the average $\bar{q} = \frac{1}{n} \sum_{i=1}^n q_i$.
3. If change in $\|\bar{q}\|$ is small, stop. Else, set $j = j + 1$ and return to Step 1.

Find μ_f by *inversion* s.t. $Q(\mu_f) = \bar{q}$.

1 inversion

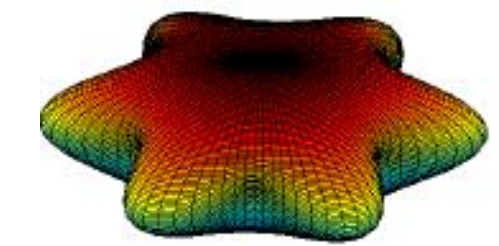
REFERENCES

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- Q. Xie, S. Kurtek, H. Le, and A. Srivastava. Parallel transport of deformations in shape space of elastic surfaces. ICCV 2013.
- I.H. Jermyn, S. Kurtek, E. Klassen, and A. Srivastava. Elastic shape matching of parameterized surfaces using square root normal fields. ECCV, 5(14):805–817, 2012.
- S. Kurtek, E. Klassen, J.C. Gore, Z. Ding and A. Srivastava. Elastic Geodesic Paths in Shape Space of Parameterized Surfaces. PAMI, 34(9):1717-1730, 2012.

Approximated Inversion Map

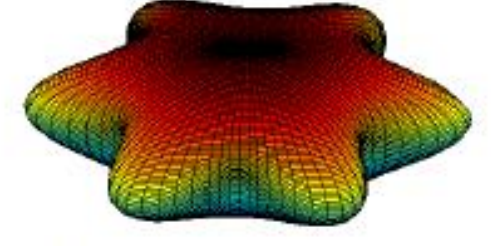
- Given q_o , find f^* to approximate the ground truth f_o , s.t. $Q(f_o) = q_o$.

Ground Truth (f_o)

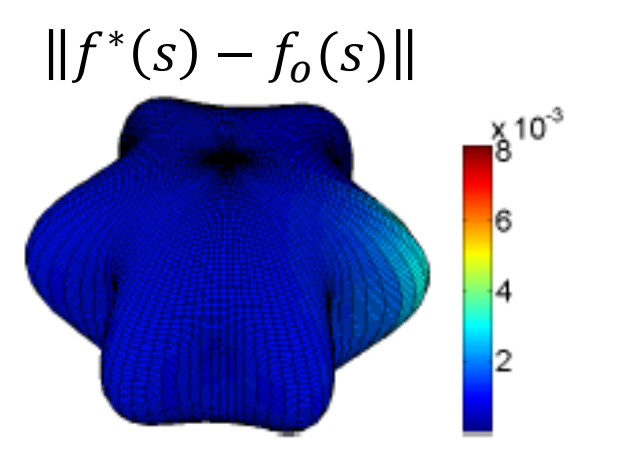
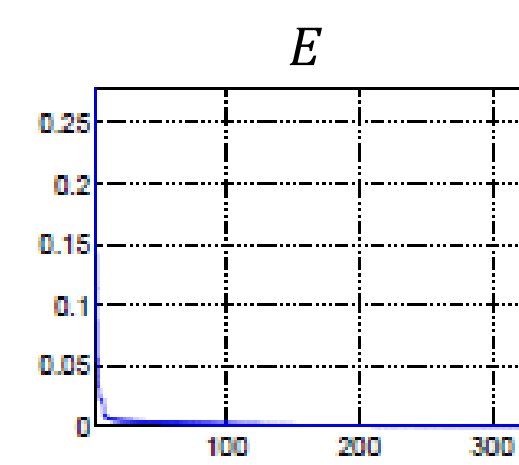


$E(f_o; q_o) = 0$

Numerical Solution (f^*)



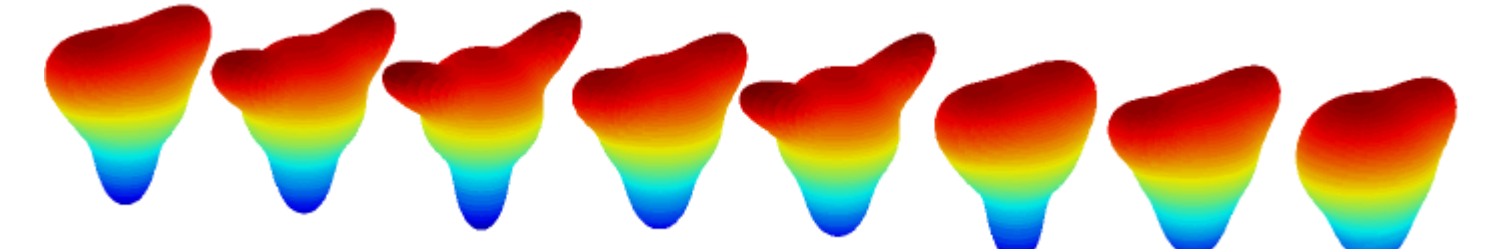
$E(f^*; q_o) = .9E-4$



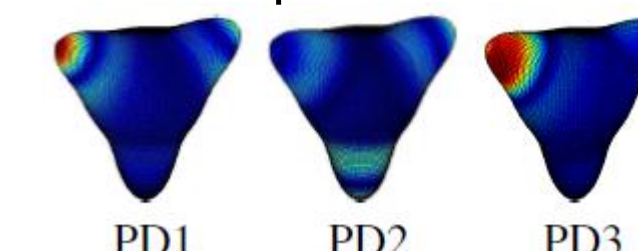
Statistical Analysis

- Given a sample of observed surfaces f_1, \dots, f_n . Estimate the mean shape and principal directions of variation

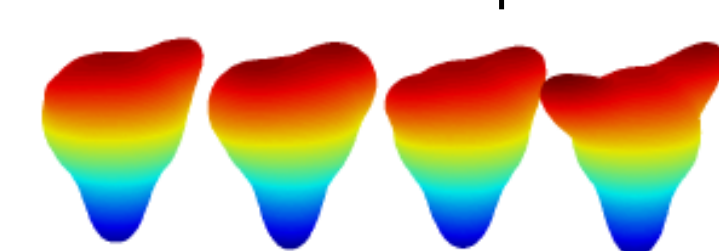
Observations



Principal Directions



Random Samples



ADHD Classification

- Using shapes of subcortical structures in human brain to detect and quantify presence of the attention deficit hyperactivity disorder (ADHD)
- 19 with ADHD and 15 non-ADHD
- Gaussian classifier on principal components

Method	SRNF Gauss	SRM Gauss	SRM NN	Harmonic	ICP	SPHARM PDM
Structure (%)	Proposed	[29]	[19]		[5]	[13]
L. Caudate	67.7	-	41.2	64.7	32.4	61.8
L. Pallidus	85.3	88.2	76.5	79.4	67.7	44.1
L. Putamen	94.1	82.4	82.4	70.6	61.8	50.0
L. Thalamus	67.7	-	58.8	67.7	35.5	52.9
R. Caudate	55.9	-	50.0	44.1	50.0	70.6
R. Pallidus	76.5	67.6	61.8	67.7	55.9	52.9
R. Putamen	67.7	82.4	67.7	55.9	47.2	55.9
R. Thalamus	67.7	-	58.8	52.9	64.7	64.7